### **Professor Rikard Söderberg**

Head of Department of Industrial and Materials Science

Director for Wingquist Laboratory

Chairman of the board for Fraunhofer Chalmers Centre (FCC)

Research Leader Geometry Assurance & Robust Design

Founder of RD&T Technology





## **Research Groups**



#### Systems Engineering and PLM

Lean development processes supported by IT-based methods & tools



Geometry and Motion Planning Math based algorithms and software for efficient product and production development





Minimizing the effect of geometrical variation in assembled products



Automation Virtual development and integration of product, production and automation systems



#### Geometry Assurance & Robust Design Group

- Rikard Söderberg, Professor, Research Group Leader
- Lars Lindkvist, Associate Professor
- Kristina Wärmefjord, Associate Professor
- Alf Andersson, Adjunct Professor (VCG)
- Andreas Dagman, PhD, lecturer
- Casper Wickman, PhD, industrial post-doc (VCG)
- Johan Lööf, PhD, industrial post-doc (GKN)
- Johan Vallhagen, PhD, industrial post-doc (GKN)
- Anders Forslund, PhD, post-doc (Chalmers)
- Johan Carlson, PhD, FCC
- Fredrik Edelvik, PhD, FCC
- Samuel Lorin, PhD, FCC
- Cristoffer Cromvik, PhD, FCC

- Björn Lindau, industrial PhD student (VCC)
- Peter Edholm, PhD student
- Mikael Rosenqvist, PhD student
- Julia Madrid, PhD student
- Konstantinos Stylidis, PhD student
- Soner Camuz, PhD student
- Tomas Hermansson, PhD student, FCC
- Domenico Spensieri, PhD student, FCC
- Vaishak Sagar, PhD student
- Roham Tabar, PhD student
- Abolfazl Rezaei Aderiani, PhD student
- Mohsen Bayani, industrial PhD student (VCC)
- Julia Orlowska, PhD student





## **Geometrical Variation**

Geometrical variation on individual parts (form and size), as well as assembly variation, affects requirements on:







## Tolerances - the key to mass production



Honoré Blanc, French gunsmith



Firearms with **interchangeable** flint locks, 1778.





The concept of **interchangeability** was **crucial** to the introduction of the **assembly line** at the beginning of the 20th century.





Ford assembly line, 1913.

## **Geometry Assurance**



Geometry Assurance is the set of activities that aims to minimizing the effect of geometrical variation in the final product.



• OLP of inspection devices

Geometry assurance is to a great extent supported by simulation and digital tools





# **RD&T** Geometry Assurance Toolbox

- minimizing the effect of geometrical variation



## Two main "parameters"



### Locating schemes

- Lock 6 DOFs in space
- Control robustness

### Tolerances

- Define allowed variation
- Control cost



## **RD&T** Software





## **Stability Analysis**





Identifies sensitive areas





## **Stability Analysis**





Reduced sensitivity – reduces variation





## **Statistical Variation Simulation**



How much variation in critical dimensions?





## **Contribution Analysis**

| Variation Results for Y352_HDR_RS_reduced.rdt   | Contribution Results for Y352 HDR RS reduced.rdt   | X   |
|---|--|-----|
| All Measures Previous Next Flush_L  | Measure<br>Variation   |     |
| Type: Point to Point distance. Direction: Vector: 0.78, 0.24, 0.57  | All Measures Previous Next Flush_L   |     |
| Description: Points: Tailgate Screen\MP L   | Type: Point to Point distance.   | t   |
| Ref. Points: RR Light - Lens Red\MP_L<br>Alt, Asbl.:  | Direction: Vector: 0.78, 0.24, 0.57  | Ind |
| Results<br>Runs 1000 LDL UDL  | Description:   |     |
| Mean 0.0288   | Points: Tailgate Screen\MP_L   |     |
| STD 1.49  | Ref. Points: RR Light - Lens Red\MP_L  | -   |
| 6 STD 8.92<br>8 STD 11.9  | Part Point/Arc Tolerance Ray Contribut Tol. Dir.   |     |
| Range 9.71<br>Min -4.94   | XX - Uniside RR Light A3 RR Light A3 2.0 57.7% 1.0, 0  | 7   |
| Max 4.78<br>Rel. Min -4.93  | XX - Uniside KK Light A2_2_2 KK Light A2_2_2 KK Light A2_2_2 U 35.0% 1.0, 0                  | ┛║  |
| Rel. Max 4.78   | RR Ligh MP_L Surf RR Light 3.0 3.8% 1.0, 0   |     |
| -5.92 0.0288 5.97   | XX - Uniside         RR Light A1         RR Light A1         2.0         3.0%         0.6, 0 |     |
| Lower Upper<br>Col: 0.442 Abs -2 Abs -2 Lower Out 9%  | Tailgate         MP_L         Surf RW         1.0         0.4%         1.0, 0                |     |
| Cp 0.449 Rel -2 Rel 2 Upper Out 8.8%  | XX - Uniside         RR Light B1         RR Light B1         2.0         0.1%         0.1, 0 |     |
| Pick Iteration Value Sigma Probability Offset -0.000734   |  |     |
| Use MP Tol  |  |     |
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What are the main contributors to variation?





# **RD&T** Non-rigid Variation Simulation

- Parts are allowed to bend during assembly due to errors in part geometries and fixtures
- FEA-based, including:
  - Over-constrained locating schemes
  - Forces, deformations and spring back
  - Contact modeling
  - Joining sequence
  - Stress
  - Heat
  - Gravity
  - Composites
  - Welding
- Monte Carlo Simulation (statistical)

















## **Combining Welding and Variation Simulation**

- Traditionally, welding simulation is performed on nominal models
- However, variation stemming from welding is depended on geometrical variation in parts and assembly fixtures
- The effect of welding can not be added to the effect of geometrical variation (non-linear problem)

Pahkamaa, A., Wärmefjord, K., Karlsson, L., Söderberg, R. & Goldak, J., 2012, Combining Variation Simulation With Welding Simulation for Prediction of Deformation and Variation of a Final Assembly, *Journal of Computing and Information Science in Engineering*, 12:2.









## **RD&T** Showroom

#### Visualization of variation simulation



- Requirement definition
- Visual evaluation
- Decision-making in early phases





- Textures
- Materials
- Illumination
- Reflections
- Shadows
- Viewing angles
- Environments







## Geometry Assurance Toolbox

- minimizing the effect of geometrical variation



## **Inspection Point Reduction**

- Cluster analysis used for reducing the number of inspection points.
- Based on correlations between inspection points and a measure of information.
- Working procedure:
  - 1. Load measurement data.
  - 2. Specify what points that must not be removed.
  - 3. Conduct cluster analysis.
  - 4. One representative for each cluster is then inspected.

#### **Case study: Ringframe**

189 inspection points  $\rightarrow$  14 inspection points (7 %)









## RD&T/IPS

### Efficient Geometry Inspection and off-line Programming

#### **Basic functionality**

- parameterized inspection rules
- automatic generation of collision free motions
- sequence optimization of cycle time
- DMIS viewer
- easy alignments and advanced constructions
- supports twin inspection
- easy feature accessibility analysis
- minimizing probe configurations
- support for CMM, scanners and robots

25% faster programs90% reduced programming time







## **Inspection Database**

- Statistical analysis
- Visualization of data
- Reuse of inspection data (morphing)
- Web-interface
- Closed-loop link to variation simulation



















## **RD&T Engineering Documents**









# **Towards Digital Twins**

- Competition and sustainability drive
  - quality
  - flexibility
  - factory throughput
  - equipment utilization
  - reduced energy consumption
- Simulation can leverage on
  - faster optimization algorithms
  - increased computer power
  - amount of available data

#### • Digital Twins

- support development
- enable real-time control & optimization
- allow moving from mass production to more individualized production







## Digital Twin for Geometry Assurance

- A digital product description is nominal
- A real product is never nominal (includes variation)



- The manufacturing process adds variation to the final product
- A Digital Twin of the final product should include impact from manufacturing.



Part variation from stamping

Variation from assembly

Variation from joining

Variation in final product





## What if scan data on individual parts were available in-line

- Sorting and matching of parts (selective assembly)
- Adjusting the fixtures to compensate for part errors
- Optimizing welding sequence to compensate for part errors
- Feed-back (learning) loop to improve the model











## **Digital Twin for Geometry Assurance**



Söderberg, R, Wärmefjord, K, Carlson, J, Lindkvist, L., 2017, Toward a Digital Twin for real-time geometry assurance in individualized production, *CIRP Annals - Manufacturing Technology*, 66/1:137-140.





## Selective Assembly in Non-rigid Assemblies







## Virtual (locator) Trimming



#### 1. Statistical variation analysis

Variation in critical dimensions due to form errors on individual parts can be statistically analysed (for batches or for individual assemblies).

Input: scan data for individual parts



#### 2. Virtual (locator) trimming

Form errors on individual parts are compensated by changing the position of the locators (for batches or for individual assemblies).

Input: scan data for individual parts

Söderberg, R., Lindkvist, L., Wärmefjord, K., Carlson, J. S., 2016, "Virtual Geometry Assurance Process and Toolbox," Procedia CIRP, 43, pp. 3-12





## Joining sequence optimization



#### Different joining sequences - different geometrical quality

Wärmefjord, K., Söderberg, R., Lindau, B., Lindkvist, L., Lorin, S., 2016, "Joining in Nonrigid Variation Simulation," Computeraided Technologies - Applications in Engineering and Medicine





## Towards a Digital twin for geometry assured welded structures

- Scanning of all individual parts
- Sorting and matching of parts (selective assembly)
- Adjusting the fixtures to compensate for part errors
- Optimizing welding sequence to compensate for part errors
- Scanning of welded assembly refinement of model







# Summary

- The manufacturing process adds variation to the final product
  - Part variation (forming, machining...)
  - Assembly variation (fixtures, robots, operators..)
  - Joining variation (welding, riveting...)
- The **Geometry Assurance** process aims at minimizing the effect of geometrical variation in the final product
- A **Digital Twin** for geometry assurance can use inspection data from the parts to compensate in the assembly
  - Selective assembly (matching of parts)
  - Virtual trimming/shimming (adjusting the fixture)
  - Joining sequenze optimization (spot weld sequenze)







